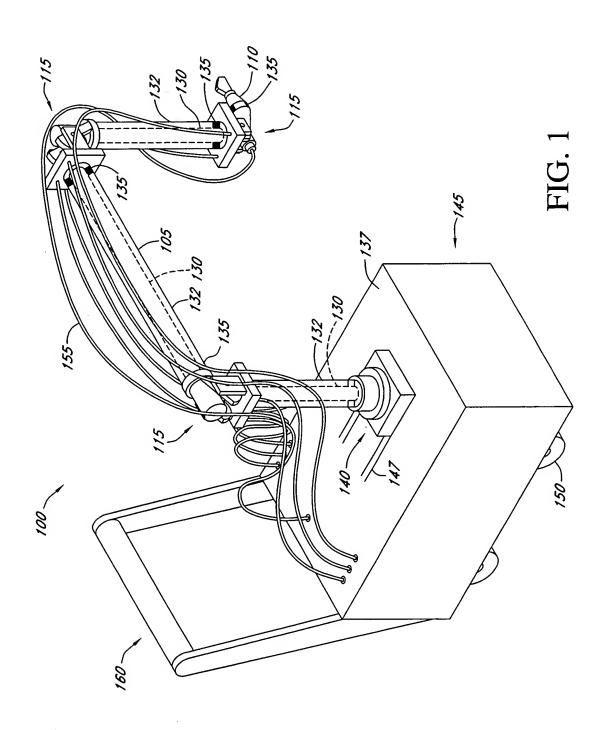
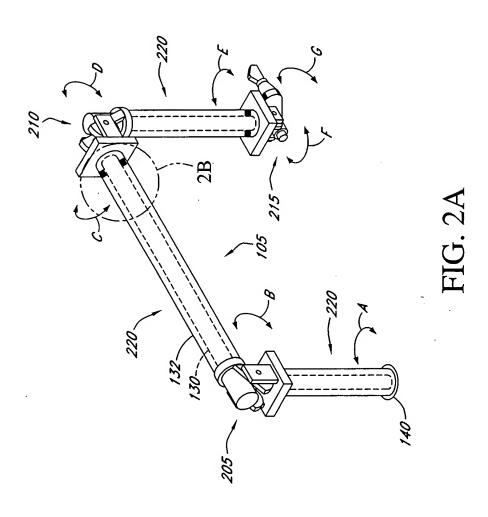
AUTOMATED ROBOTIC MEASURING SYSTEM Homer Eaton pl. No.: Unknown Atty Docket: ROMINC.004A

Appl. No.: Unknown



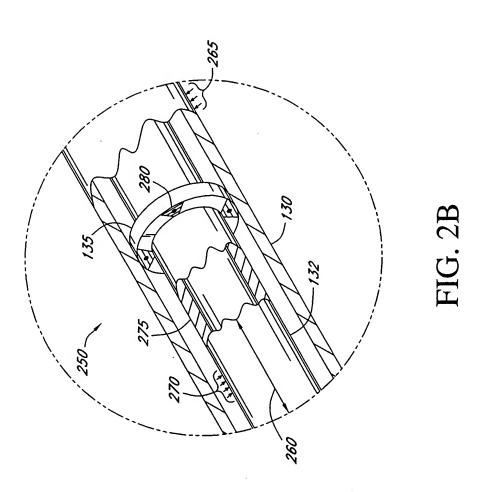
AUTOMATED ROBOTIC MEASURING SYSTEM

Homer Eaton
Atty Docket: ROMINC.004A Appl. No.: Unknown



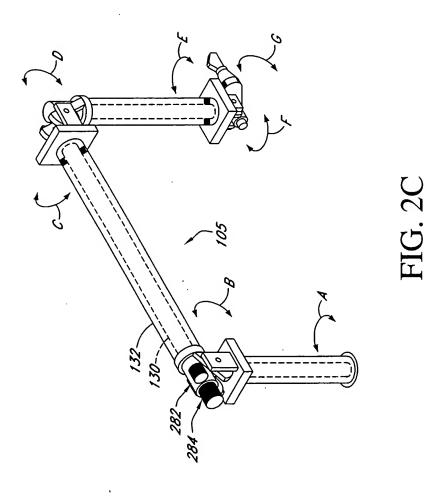
AUTOMATED ROBOTIC MEASURING SYSTEM Homer Faton

Homer Eaton
Appl. No.: Unknown Atty Docket: ROMINC.004A

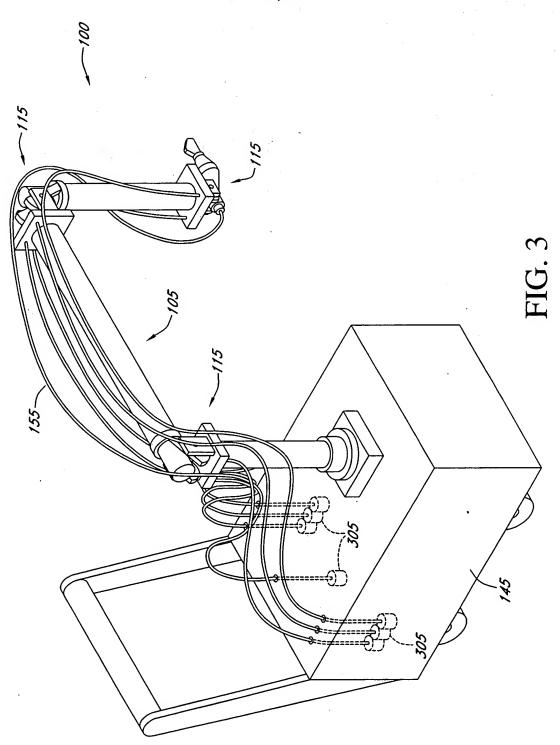


AUTOMATED ROBOTIC MEASURING SYSTEM Homer Eaton pl. No.: Unknown Atty Docket: ROMINC.004A

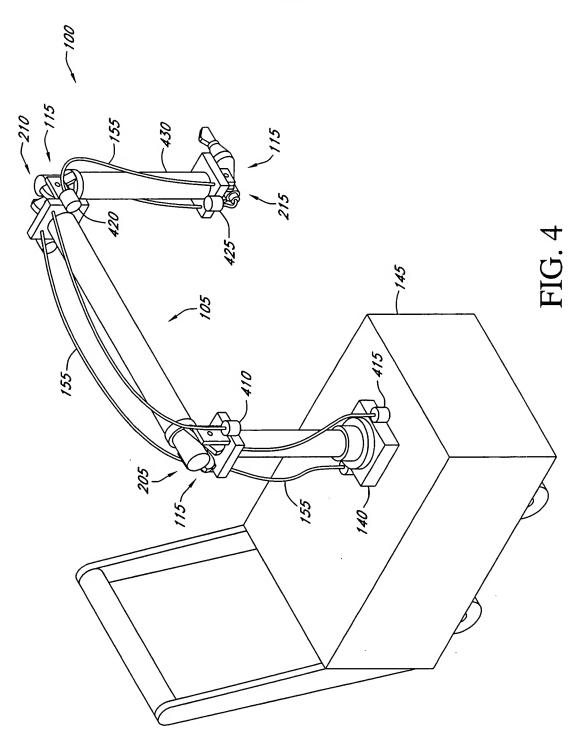
Appl. No.: Unknown



AUTOMATED ROBOTIC MEASURING SYSTEM
Homer Eaton
pl. No.: Unknown Atty Docket: ROMINC.004A Appl. No.: Unknown



AUTOMATED ROBOTIC MEASURING SYSTEM Homer Eaton Appl. No.: Unknown Atty Docket: ROMINC.004A



Homer Eaton

Appl. No.: Unknown Atty Docket: ROMINC.004A



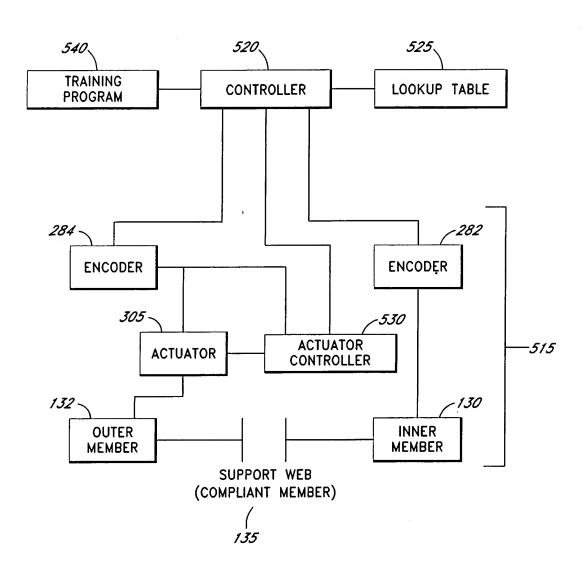


FIG. 5

Appl. No.: Unknown Atty Docket: ROMINC.004A



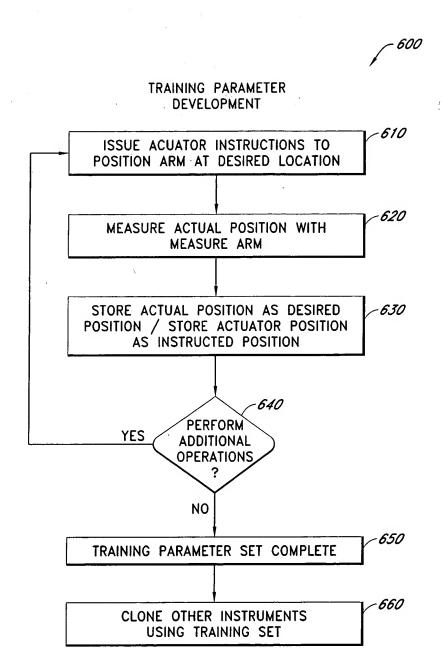


FIG. 6

Appl. No.: Unknown

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720 Gear Ratio (Outer Member)	400	400	400	400	200	200	100
$725 \smile ext{Encoder Resolution}$ (Outer Member / cycles per revolution)	1000 olution)	1000	1000	1000	1000	1000	1000
730 — Encoder Resolution 5000 (Inner Member / cycles per revolution)	5000 (ution)	2000	2000	2000	2000	2000	2000
735 Articulation Angle (Outer Member)	. 06	20°	30 °	-10 °	° 06	° 06-	. 09
$705 \sim$ Actuator Position (Encoder Cycles)	100,000.00	100,000.00 22,222.22	333,333.33	333,333.33 -11,111,11	50,000.00	-50,000.00	16,667.67
710 Unner Member (Encoder Cycles)	1250.00	277.73	416.67	-138.89	1250.00	-1250.00	-833.33